

# Stepless Reverse Flow Control

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Compressor Control Workshop

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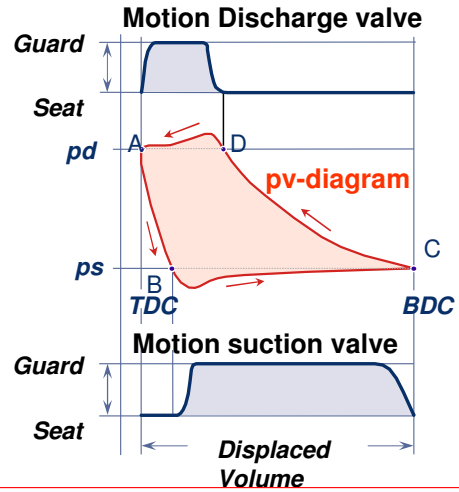
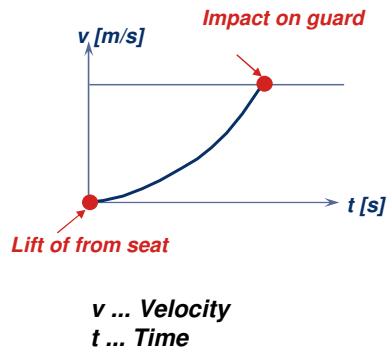
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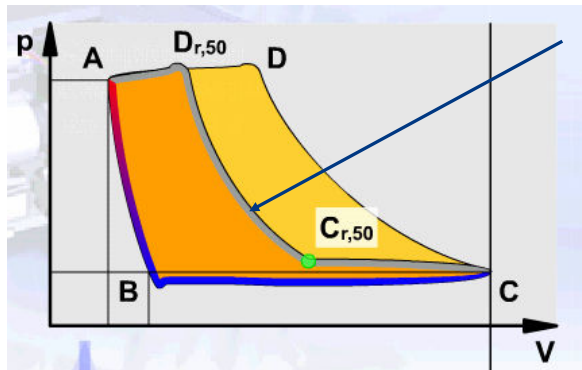


# Valve Motion at Full load

pV and lift diagram of valve sealing element:



# Reverse Flow Principle

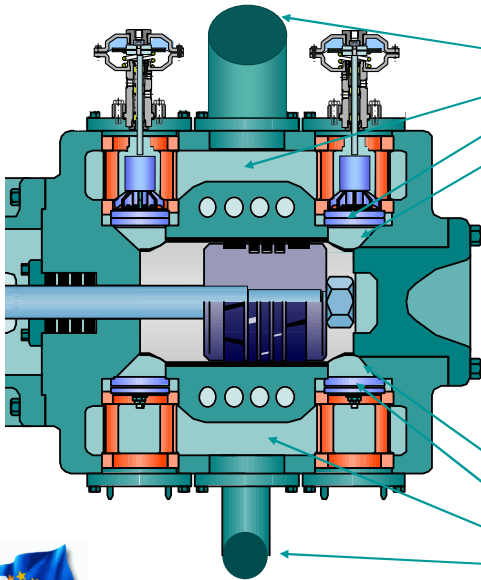


The start of compression is delayed. Part of the gas sucked in during suction stroke is pushed back.

Area enclosed by pV graph is equivalent to the energy consumed.

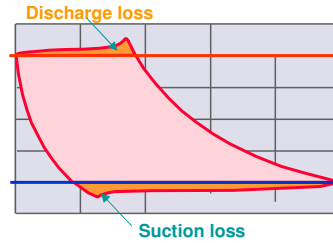


# Valve losses at full load



## Suction losses caused by:

- Piping
- Suction chamber
- Suction valve
- Valve nest

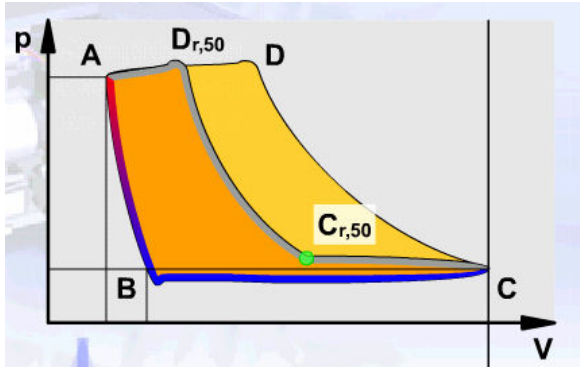


## Discharge losses caused by

- Discharge valve nest
- Discharge valve loss
- Discharge chamber
- Piping



# Valve losses at reverse flow



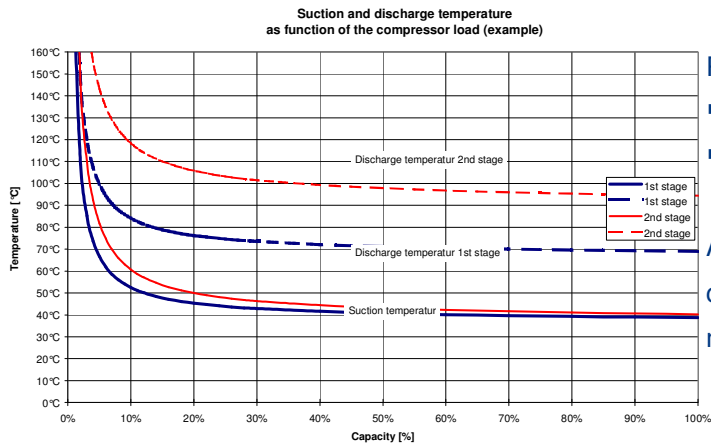
The losses at 50% part load are:

- 100% suction valve loss
- 50% reverse flow loss
- 50% discharge loss

Approx. same loss as at full load, but reduced capacity



# Temp. increase at reverse flow



Power loss generates heat:

- Suction temp. increase
- Discharge temp. increase

At 0% load the compressor can be operated for 5 to 15 minutes.



# Systems based on reverse flow principle

- Pneumatic control systems

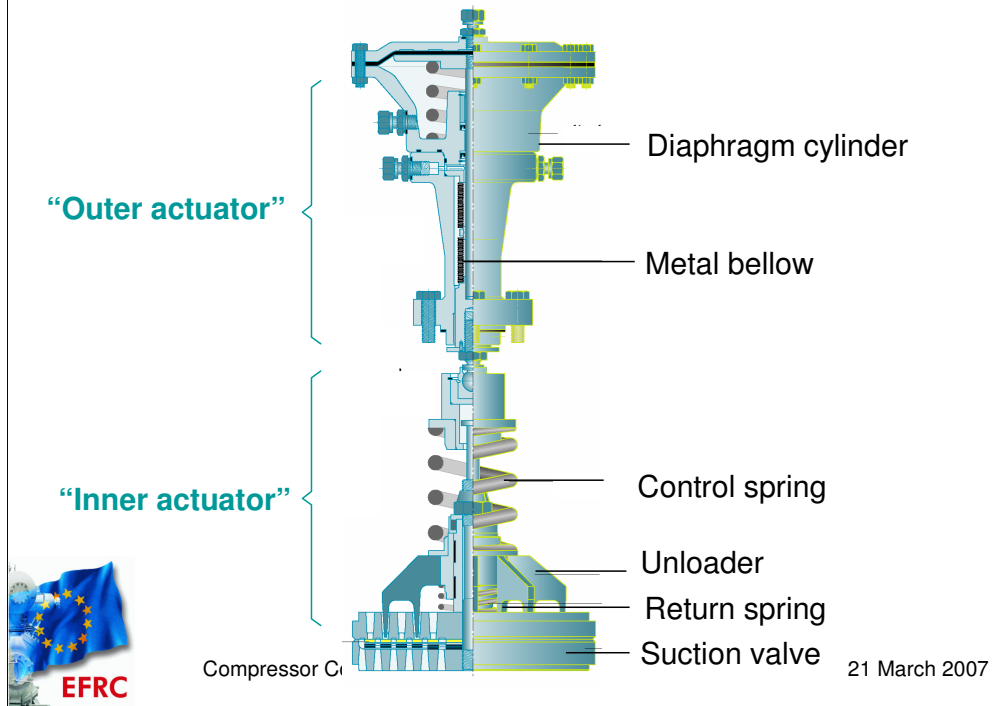


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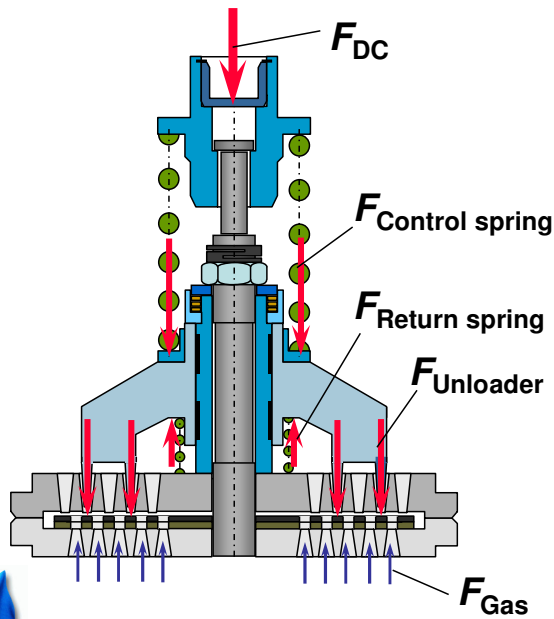
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## Components of a pneumatic actuator



## Principle of Operation



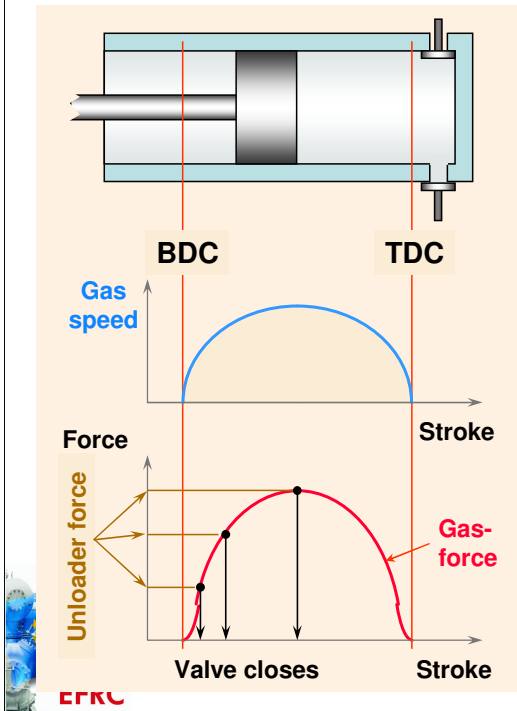
- Unloading force acts via control spring to unloader fingers
- Suction valve plate is forced to remain open
- If reverse gas flow exceeds unloader force the valve closes  
 $F_{\text{Gas}} > F_{\text{Unloader}}$
- The valve snaps open if unloader force exceeds the max. gas force



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## Theoretical Background



- Valve closes if

$$F_{\text{Gas}} > F_{\text{Unloader}}$$

- Gas force

$$F_{\text{Gas}} = \zeta \cdot \rho \cdot \frac{v_{\text{Gas}}^2}{2} \cdot A_0$$

Closing time of the valve plate depends on:

- piston speed

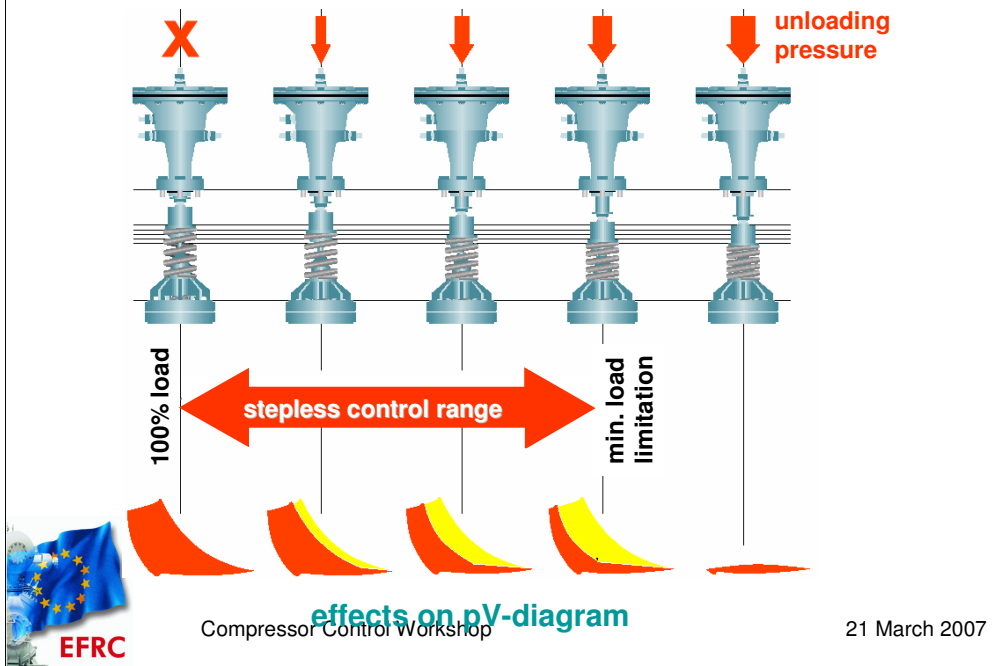
$$v_{\text{Gas}} \sim v_{\text{Piston}}$$

- gas density

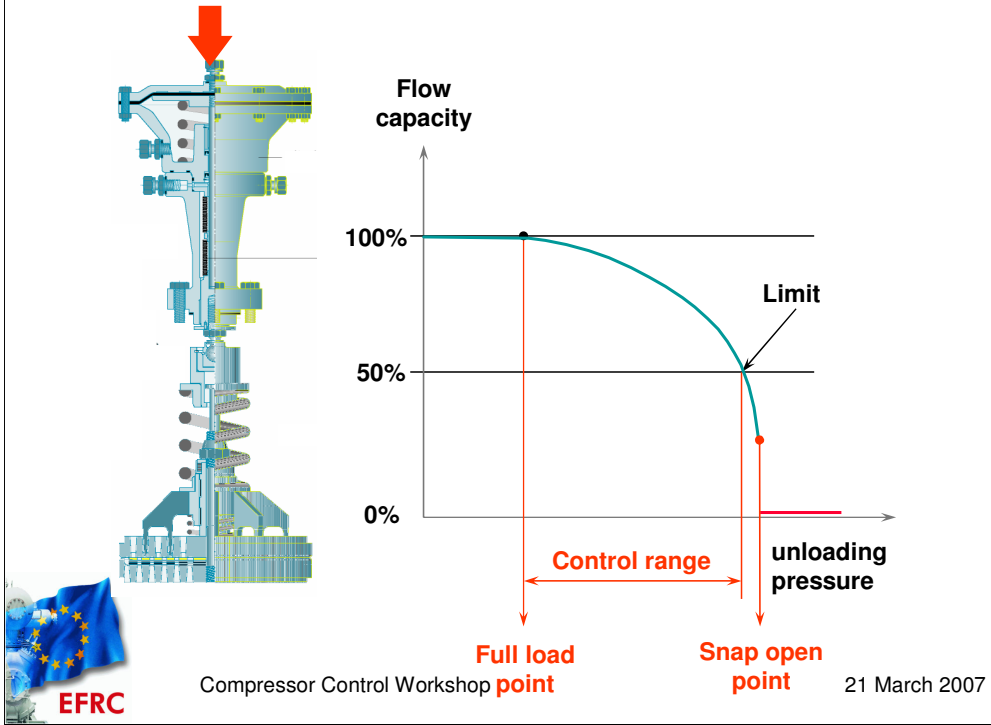
$$\rho = \frac{1}{R} \cdot \frac{p_{\text{suct}} \cdot M}{T_{\text{suct}}}$$

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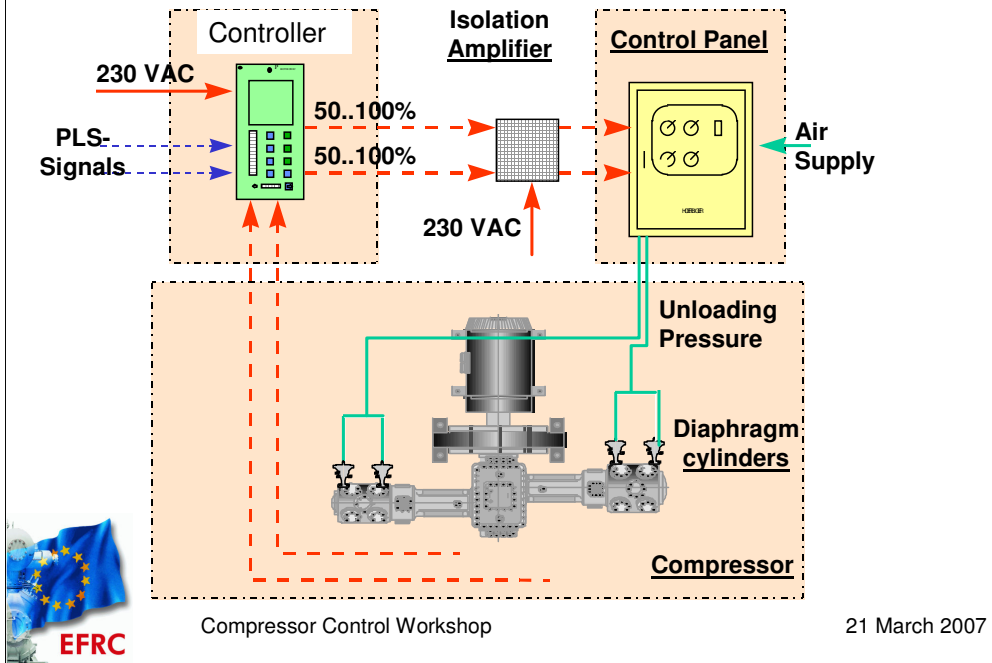
# Unloading Pressure - Load



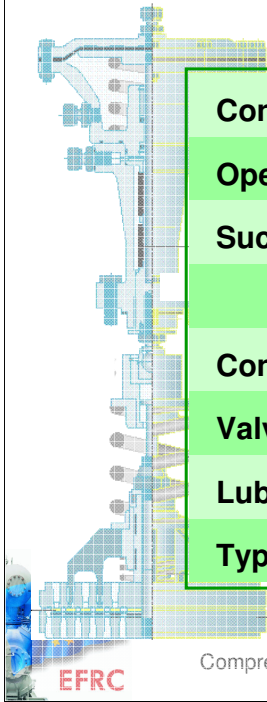
# Unloading Pressure - Load



# The Pneumatic System



## Pneumatic System - Application Range



<b>Control range</b>	<b>100% ... 50%</b>
<b>Operational conditions</b>	<b>constant</b>
<b>Suction pressure</b>	<b>up to 60 bar</b>
<b>Control</b>	<b>electronically</b>
<b>Valve plate material</b>	<b>Steel pref.</b>
<b>Lubrication</b>	<b>lube</b>
<b>Typical applications</b>	<b>Process industry</b>

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# Systems based on reverse flow principle

- Hydraulic/Electronic systems

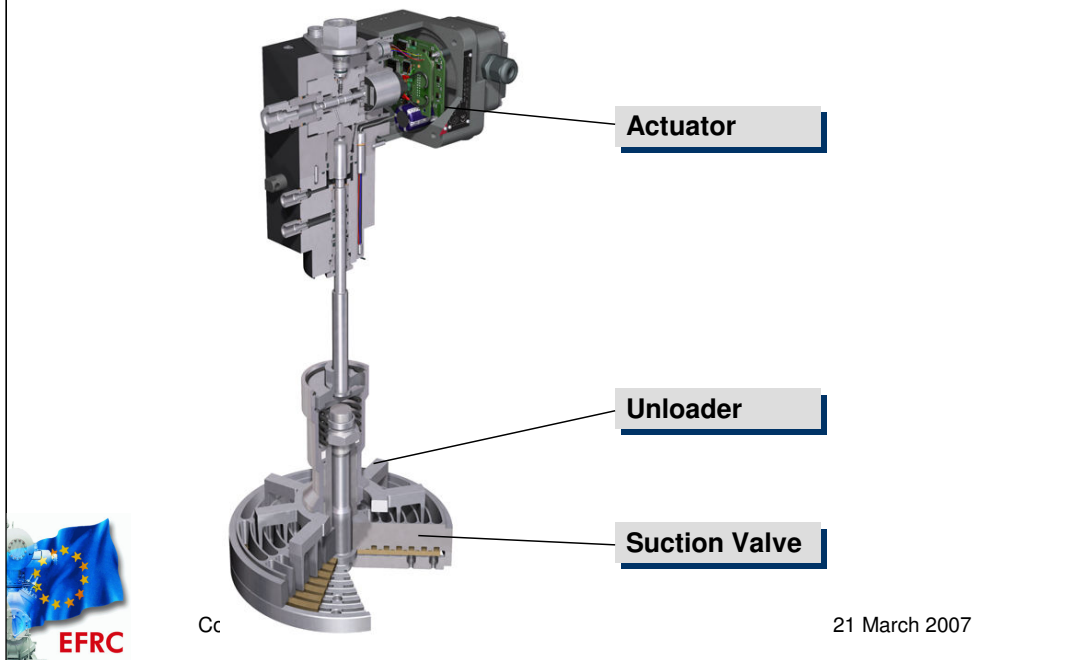


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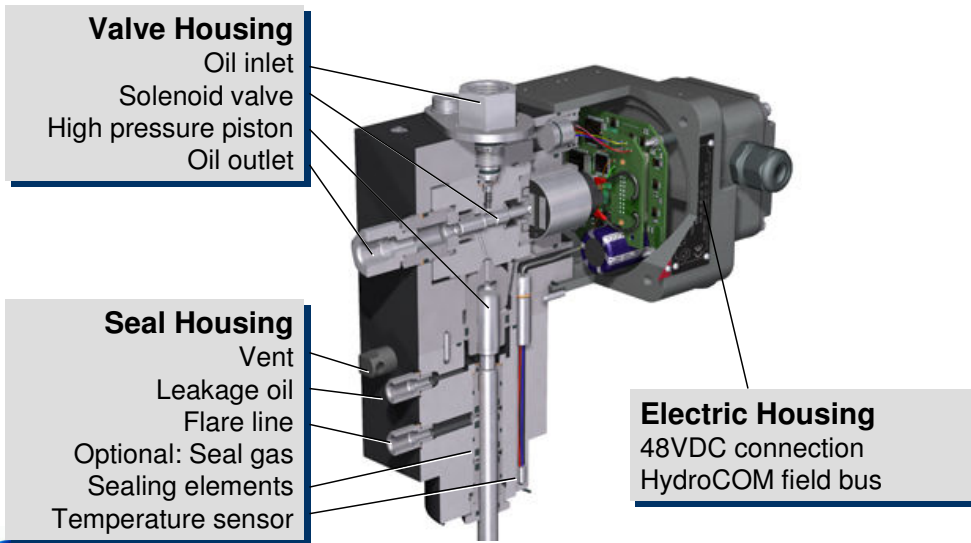
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## Components of HydroCOM Actuator



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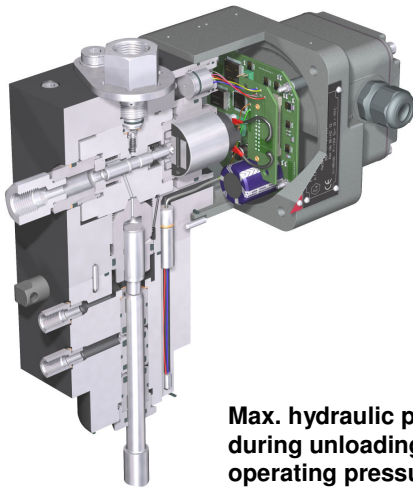


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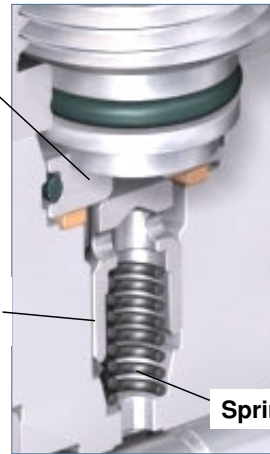
## Valve housing – Check valve



Valve seat

Valve piston

Spring



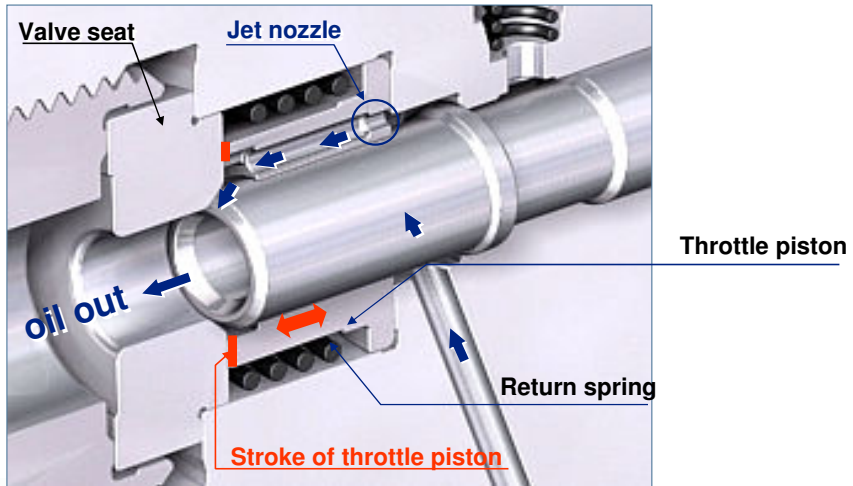
**Max. hydraulic pressure in actuator during unloading > hydraulic unit operating pressure  
=> Check valve integrated**



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## Valve housing – Soft touch damper



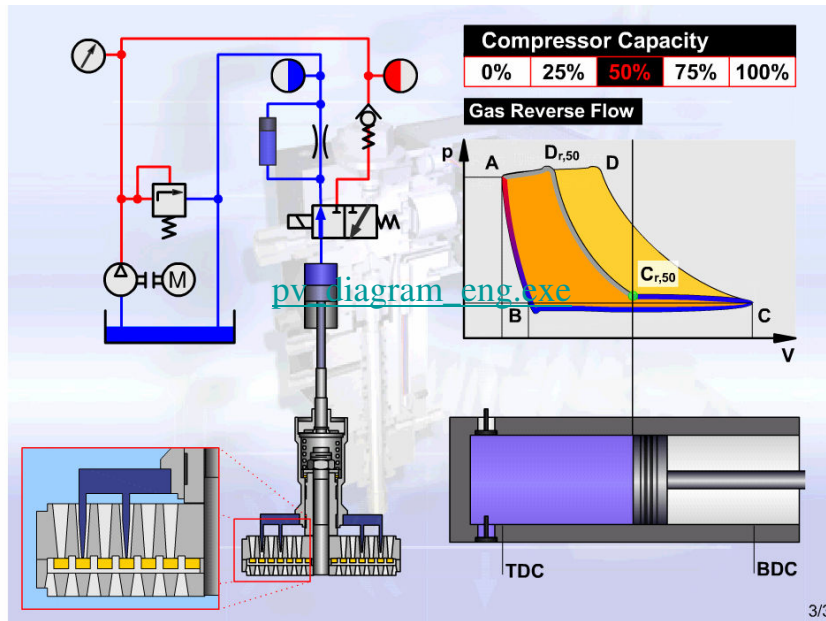
## Components of HydroCOM Actuator



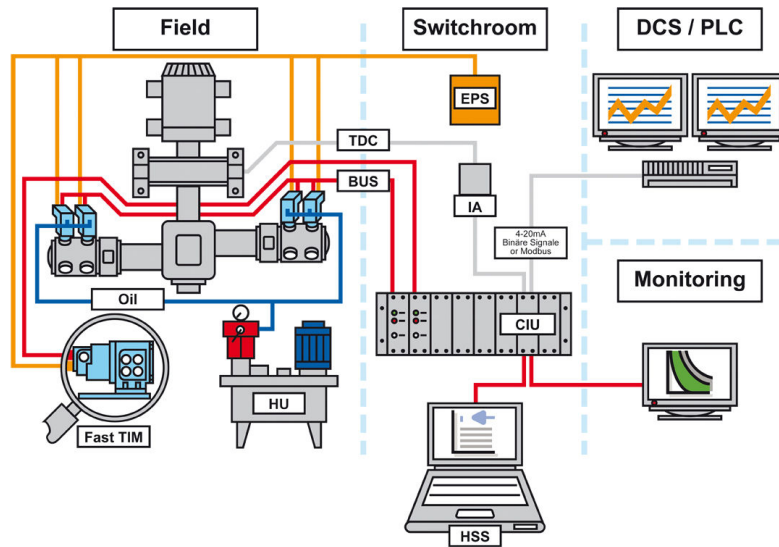
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# Working principle



# HydroCOM System Layout



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## HydroCOM Application Range

Control range	(0..) 10*...100%
Max. suction pressure	160bar
Max. suction temperature	120 °C
Max. compressor speed	1200 rpm
Non-lube, corrosive gases	yes
Suction valve sealing element	ring, plate
Gases	All, except O <sub>2</sub> + acetylen
Ex-certification ATEX, Japan	ExII 2G EEx de IIB + H2 T4
Ex-certification Canada (CSA)	Class I, Div.1, Gr. A, B, C, D
Ex-certification US (FM)	Class I, Div.1, Gr. B, C, D, T4 AEx d,e IIB + H2 T4





# Systems based on reverse flow principle

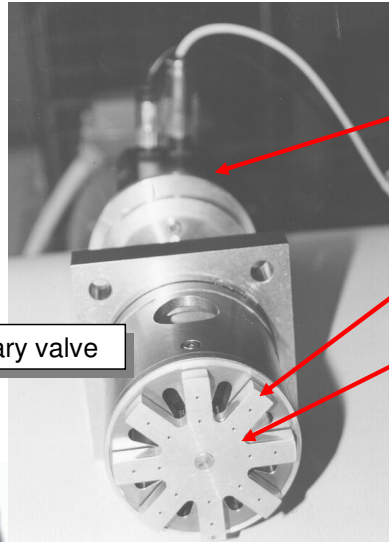
- Rotary valve



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# Rotary Valve



Electronic driver

Valve seat

Valve guard => rotor + sealing element

Rotary valve requires active valve control;

Rotary valve



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